

ON THE LINEAR PARTIAL DIFFERENTIAL EQUATION OF SECOND ORDER IN N INDEPENDENT VARIABLES WITH CONSTANT COEFFICIENT

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§1. The proposed equation is of the form:

$$(1.1) \quad \sum_{i,j=1}^n a_{ij} \frac{\partial^2 w}{\partial x_i \partial x_j} + \sum_{i=1}^n a_i \frac{\partial w}{\partial x_i} + a_0 w = f(x_1, x_2, \dots, x_n),$$

where $a_0, a_i, a_{ij}(=a_{ji}), i=1, 2, \dots, n$ are given real constant, and $f(x_1, x_2, \dots, x_n)$ is a given integrable function.

First we intend to find the complementary function, *i.e.* the general integral of

$$(1.2) \quad \sum_{i,j=1}^n a_{ij} \frac{\partial^2 w}{\partial x_i \partial x_j} + \sum_{i=1}^n a_i \frac{\partial w}{\partial x_i} + a_0 w = 0.$$

We commence with a particular case, such that the lefthanded side is resolvable into linear factors as

$$(1.3) \quad \left(\sum_{i=1}^n b_i \frac{\partial}{\partial x_i} + b_0 \right) \left(\sum_{j=1}^n c_j \frac{\partial}{\partial x_j} + c_0 \right) w = 0,$$

where b 's, c 's are constants, and, since (1.1) is assumed to be really of second order, at least one among a_{ij} and accordingly one of b_i and c_j should be non-zero, so that conveniently let it be $b_1 c_1 \neq 0$.¹⁾

Since the factors of product in (1.3) are commutative, the required complementary function shall be found by solving

$$(1.4) \quad \left(\sum_{i=1}^n b_i \frac{\partial}{\partial x_i} + b_0 \right) w = 0,$$

or

$$(1.5) \quad \left(\sum_{j=1}^n c_j \frac{\partial}{\partial x_j} + c_0 \right) w = 0.$$

On writing the subsidiary equation of the partial differential equation of first order (1.4)

¹⁾ If all $a_{ii}=0$, this assumption becomes absurd, to speak more we must say that some $b_i c_j \neq 0$. But the matter being trivial, only for the sake of brevity we have assumed as above.

$$\frac{dx_1}{b_1} = \frac{dx_2}{b_2} = \dots = \frac{dx_n}{b_n} = \frac{dw}{-b_0 w},$$

where $b_1 \neq 0$, we see immediately that their solutions are

$$x_i - \frac{b_i}{b_1} x_1 = \text{const.}, \quad i = 2, 3, \dots, n,$$

and

$$w \exp \left\{ \frac{b_0}{b_1} x_1 \right\} = \text{const.},$$

so that the general integral of (1.4) is

$$(1.6) \quad w = \exp \left\{ -\frac{b_0}{b_1} x_1 \right\} \phi \left(x_2 - \frac{b_2}{b_1} x_1, \dots, x_n - \frac{b_n}{b_1} x_1 \right),$$

where ϕ denotes any arbitrary function. Quite similarly with (1.5) we get

$$(1.7) \quad w = \exp \left\{ -\frac{c_0}{c_1} x_1 \right\} \psi \left(x_2 - \frac{c_2}{c_1} x_1, \dots, x_n - \frac{c_n}{c_1} x_1 \right).$$

Therefore the required general integral of (1.2) is given by

$$(1.8) \quad w = e^{-\frac{b_0}{b_1} x_1} \phi \left(x_2 - \frac{b_2}{b_1} x_1, \dots, x_n - \frac{b_n}{b_1} x_1 \right) + e^{-\frac{c_0}{c_1} x_1} \psi \left(x_2 - \frac{c_2}{c_1} x_1, \dots, x_n - \frac{c_n}{c_1} x_1 \right),$$

where ϕ and ψ are arbitrary functions.

In the case, that all $b_i = c_i$, however (1.3) becomes

$$(1.9) \quad \left(\sum_{i=1}^n b_i \frac{\partial}{\partial x_i} + b_0 \right)^2 w = 0,$$

and the corresponding solution (1.8) contains essentially only one arbitrary function, so that it ceases to be general. To obtain the general integral, let us put

$$\left(\sum_{i=1}^n b_i \frac{\partial}{\partial x_i} + b_0 \right) w = v,$$

and solve

$$\left(\sum_{i=1}^n b_i \frac{\partial}{\partial x_i} + b_0 \right) v = 0.$$

In view of (1.6) the latter's general integral is

$$v = \exp \left\{ -\frac{b_0}{b_1} x_1 \right\} \phi \left(x_2 - \frac{b_2}{b_1} x_1, \dots, x_n - \frac{b_n}{b_1} x_1 \right),$$

and accordingly we have to solve

$$\left(\sum_{i=1}^n b_i \frac{\partial}{\partial x_i} + b_0 \right) w = \exp \left\{ -\frac{b_0}{b_1} x_1 \right\} \phi \left(x_2 - \frac{b_2}{b_1} x_1, \dots, x_n - \frac{b_n}{b_1} x_1 \right).$$

With regard to this linear partial differential equation of first order the subsidiary

equations become

$$\frac{dx_1}{b_1} = \frac{dx_2}{b_2} = \dots = \frac{dx_n}{b_n} = \frac{dw}{\exp\left\{-\frac{b_0}{b_1}x_1\right\} \phi\left(x_2 - \frac{b_2}{b_1}x_1, \dots, x_n - \frac{b_n}{b_1}x_1\right) - b_0 w},$$

whose solutions are $n-1$ equations

$$x_i - \frac{b_i}{b_1}x_1 = k_i \quad (i = 2, 3, \dots, n),$$

where k_i are arbitrary constants, and one more equation that is obtainable from

$$\frac{dw}{dx_1} + \frac{b_0}{b_1}w = \frac{1}{b_1} \exp\left\{-\frac{b_0}{b_1}x_1\right\} \phi(k_2, \dots, k_n),$$

i. e.

$$w \exp\left\{\frac{b_0}{b_1}x_1\right\} - \frac{x_1}{b_1} \phi(k_2, \dots, k_n) = k_1,$$

where $k_i = x_i - \frac{b_i}{b_1}x_1$ ($i=2, 3, \dots, n$), and $\frac{1}{b_1} \phi$ can be written simply ϕ as an arbitrary function. Therefore the general integral of (1.9) is

$$(1.10) \quad w = \exp\left\{-\frac{b_0}{b_1}x_1\right\} \left[x \phi\left(x_2 - \frac{b_2}{b_1}x_1, \dots, x_n - \frac{b_n}{b_1}x_1\right) + \psi\left(x_2 - \frac{b_2}{b_1}x_1, \dots, x_n - \frac{b_n}{b_1}x_1\right) \right],$$

where ϕ and ψ are arbitrary functions.

Next we proceed to find a particular integral of (1.1). For this purpose we put again in view of (1.3)

$$(1.11) \quad \left(\sum_{i=1}^n c_i \frac{\partial}{\partial x_i} + c_0 \right) w = u$$

and

$$(1.12) \quad \left(\sum_{i=1}^n b_i \frac{\partial}{\partial x_i} + b_0 \right) u = f(x_1, x_2, \dots, x_n).$$

Now the subsidiary equations of the latter being

$$\frac{dx_1}{b_1} = \frac{dx_2}{b_2} = \dots = \frac{dx_n}{b_n} = \frac{du}{f(x_1, \dots, x_n) - b_0 u},$$

their solutions are again

$$x_i - \frac{b_i}{b_1}x_1 = k_i \quad (i = 2, 3, \dots, n),$$

and the solution of

$$\frac{du}{dx_1} + \frac{b_0}{b_1}u = \frac{1}{b_1} f(x_1, \dots, x_n),$$

i. e.

$$u \exp \left\{ \frac{b_0}{b_1} x_1 \right\} = \frac{1}{b_1} \int \exp \left\{ \frac{b_0}{b_1} x_1 \right\} f \left(x_1, \frac{b_2}{b_1} x_1 + k_2, \dots, \frac{b_n}{b_1} x_1 + k_n \right) dx_1 + k_1.$$

Hence, on setting the additional arbitrary constant $k_1=0$, we obtain as a particular solution of (1.12)

$$(1.13) \quad u = \frac{1}{b_1} \exp \left\{ -\frac{b_0}{b_1} x_1 \right\} \int \exp \left\{ \frac{b_0}{b_1} x_1 \right\} f \left(x_1, \frac{b_2}{b_1} x_1 + k_2, \dots, \frac{b_n}{b_1} x_1 + k_n \right) dx_1,$$

where constants k_i should be replaced by $x_i - \frac{b_i}{b_1} x_1$ after integration, so that it yields

$$u = v(x_1, x_2, \dots, x_n).$$

Substituting this in (1.11) and solving it, we get a solution of (1.11), namely, a particular integral of the linear partial differential equation of second order (1.11)

$$(1.14) \quad w = \frac{1}{c_1} \exp \left\{ -\frac{c_0}{c_1} x_1 \right\} \int \exp \left\{ \frac{c_0}{c_1} x_1 \right\} v \left(x_1, \frac{c_2}{c_1} x_1 + l_2, \dots, \frac{c_n}{c_1} x_1 + l_n \right) dx_1,$$

where again l_i must be replaced by $x_i - \frac{c_i}{c_1} x_1$ after integration.

Example 1.

$$\begin{aligned} 2 \frac{\partial^2 w}{\partial x^2} + 3 \frac{\partial^2 w}{\partial y^2} - 4 \frac{\partial^2 w}{\partial z^2} - 5 \frac{\partial^2 w}{\partial x \partial y} + \frac{\partial^2 w}{\partial y \partial z} - 2 \frac{\partial^2 w}{\partial x \partial z} \\ + 8 \frac{\partial w}{\partial x} - 10 \frac{\partial w}{\partial y} - 4 \frac{\partial w}{\partial z} + 8w = yze^{-2x}. \end{aligned}$$

Factorizing the left-handed member, we get

$$\left(\frac{\partial}{\partial x} - \frac{\partial}{\partial y} + \frac{\partial}{\partial z} + 2 \right) \left(2 \frac{\partial}{\partial x} - 3 \frac{\partial}{\partial y} - 4 \frac{\partial}{\partial z} + 4 \right) w = yze^{-2x},$$

and thus $b_1=1$, $b_2=-1$, $b_3=1$, $b_0=2$, $c_1=2$, $c_2=-3$, $c_3=-4$, $c_0=4$. Hence the complementary function becomes by virtue of (1.8)

$$w = e^{-2x} \{ \phi(y+x, z-x) + \psi(2y+3x, z+2x) \},$$

while the particular integral is obtained by means of (1.13) and (1.14) as follows:

$$\begin{aligned} u &= e^{-2x} \int (k_2 - x)(k_3 + x) dx = e^{-2x} \left\{ k_2 k_3 x + \frac{1}{2} (k_2 - k_3) x^2 - \frac{x^3}{3} \right\} \\ &= e^{-2x} \left[xyz - \frac{1}{2} x^2 y + \frac{1}{2} x^2 z - \frac{1}{3} x^3 \right], \end{aligned}$$

and

$$\begin{aligned} w &= \frac{1}{2} e^{-2x} \int e^{2x} u dx \\ &= \frac{1}{2} e^{-2x} \int e^{2x} e^{-2x} \left\{ x(l_2 - \frac{3}{2}x)(l_3 - 2x) - \frac{1}{2} x^2(l_2 - \frac{3}{2}x) + \frac{1}{2} x^2(l_3 - 2x) - \frac{x^3}{3} \right\} dx \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{2} e^{-2x} \left[\frac{x^2}{2} l_2 l_3 - \frac{x^3}{3} \left(\frac{5}{2} l_2 + l_3 \right) + \frac{29}{48} x^4 \right] \\
&= \frac{1}{2} e^{-2x} \left[\frac{3}{32} x^4 + \frac{1}{12} x^3 y + \frac{5}{24} x^3 z + \frac{1}{4} x^2 y z \right].
\end{aligned}$$

It is easy to check that

$$\begin{aligned}
u &= \left(\frac{\partial}{\partial x} - \frac{\partial}{\partial y} + \frac{\partial}{\partial z} + 2 \right) w = e^{-2x} \left[\frac{x^3}{2} + 2x^2 y + \frac{3}{8} x^2 z + \frac{1}{2} x y z \right], \\
\left(2 \frac{\partial}{\partial x} - 3 \frac{\partial}{\partial y} - 4 \frac{\partial}{\partial z} + 4 \right) u &= e^{-2x} y z.
\end{aligned}$$

Example 2. Our method might be repeatedly applied *e.g.* for a linear partial differential equation of third order as

$$\left(\frac{\partial}{\partial x} - \frac{\partial}{\partial y} + \frac{\partial}{\partial z} + 2 \right) \left(2 \frac{\partial}{\partial x} - 3 \frac{\partial}{\partial y} - 4 \frac{\partial}{\partial z} + 4 \right) \left(\frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial z} + 2 \right) v = e^{-2x} y z.$$

Putting $\left(\frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial z} + 2 \right) v = w$, the problem reduces to *Ex. 1*, and w is rendered by the above result. Hence the particular integral is found similarly, as before,

$$\begin{aligned}
v &= e^{-2x} \int w dx \quad (y = x + h_2, \quad z = x + h_3) \\
&= e^{-2x} \left[\frac{1}{12} h_2 h_3 x^3 + \frac{1}{96} (8h_2 + 11h_3) x^4 + \frac{61}{480} x^5 \right] \\
&= e^{-2x} \left[\frac{x^5}{80} + \frac{7}{12} x^4 y + \frac{1}{32} x^4 z - \frac{1}{12} x^3 y z \right],
\end{aligned}$$

while the complementary function is easily found to be

$$V = e^{-2x} \{ \phi(y+z, z-x) + \psi(2y+3x, z+2x) + \theta(y-x, z-x) \},$$

where ϕ, ψ, θ are arbitrary functions.

§2. Next we shall treat the case that does not permit any factorization like (1.3). In this case we will write in a standard form the given linear partial differential equation of second order

$$(2.1) \quad \sum_{i,j=1}^n a_{ij} \frac{\partial^2 w}{\partial x_i \partial x_j} + \sum_{i=1}^n b_i \frac{\partial w}{\partial x_i} + c_0 w = f(x_1, x_2, \dots, x_n),$$

where $a_{ij} (= a_{ji})$, b_i , c_0 ($i, j = 1, 2, \dots, n$) are given real constants.

As well known, the symmetric matrix $A = (a_{ij})$ can be brought into a diagonal matrix by operating a suitably chosen orthogonal matrix T :

$$(2.2) \quad \bar{T} A T = A' = \begin{pmatrix} a'_1 & & & 0 \\ & \ddots & & \\ 0 & & \ddots & \\ & & & a'_n \end{pmatrix},$$

where

$$T = \begin{pmatrix} l_{11} & \cdots & l_{1n} \\ \vdots & & \vdots \\ l_{n1} & \cdots & l_{nn} \end{pmatrix}, \quad \bar{T} = \begin{pmatrix} l_{11} & \cdots & l_{n1} \\ \vdots & & \vdots \\ l_{1n} & \cdots & l_{nn} \end{pmatrix}$$

with $\bar{T} = T^{-1}$, $T\bar{T} = I$. If \mathfrak{x} is transformed into \mathfrak{x}' by T :

$$(2.3) \quad T\mathfrak{x} = \begin{pmatrix} l_{11} & \cdots & l_{1n} \\ \vdots & & \vdots \\ l_{n1} & \cdots & l_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} x'_1 \\ \vdots \\ x'_n \end{pmatrix} = \mathfrak{x}', \quad \text{or } \mathfrak{x} = \bar{T}\mathfrak{x}',$$

the binary quadratic form

$$(2.4) \quad Q = \sum_{i,j=1}^n a_{ij} x_i x_j = \bar{\mathfrak{x}} A \mathfrak{x} \\ = (x_1, \dots, x_n) \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \cdots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

shall be transformed into the standard form

$$(2.5) \quad \sum_{i=1}^r a'_i x_i'^2$$

where r denotes the rank of matrix A (or it may be written still $\sum_{i=1}^n a'_i x_i'^2$, but now some a'_i are allowed to be 0). By transformation (2.3) we get $x_j = \sum l_{ij} x'_i$, so that $\frac{\partial w}{\partial x'_i} = \sum_j \frac{\partial w}{\partial x_j} \frac{\partial x_j}{\partial x'_i} = \sum_j l_{ij} \frac{\partial w}{\partial x_j}$ and similarly $\frac{\partial w}{\partial x_j} = \sum_i l_{ij} \frac{\partial w}{\partial x'_i}$. Thus

$$(2.6) \quad \begin{cases} \frac{\partial}{\partial x'_i} = l_{j1} \frac{\partial}{\partial x_1} + l_{j2} \frac{\partial}{\partial x_2} + \cdots + l_{jn} \frac{\partial}{\partial x_n} & (i = 1, 2, \dots, n), \\ \frac{\partial}{\partial x_j} = l_{1j} \frac{\partial}{\partial x'_1} + l_{2j} \frac{\partial}{\partial x'_2} + \cdots + l_{nj} \frac{\partial}{\partial x'_n} & (j = 1, 2, \dots, n). \end{cases}$$

By the transformations, the quadratic differential form $\sum_{i,j=1}^n a_{ij} \frac{\partial}{\partial x_i} \frac{\partial}{\partial x_j} w$ in (2.1) could be brought into $\sum_{i=1}^n a'_i \frac{\partial^2 w}{\partial x_i'^2}$. At the same time, the linear differential form in (2.1) would be transformed into

$$(2.7) \quad \sum_{j=1}^n b_j \frac{\partial w}{\partial x_j} = \sum_j b_j \sum_i l_{ij} \frac{\partial w}{\partial x'_i} = \sum_i (\sum_j l_{ij} b_j) \frac{\partial w}{\partial x'_i} = \sum_i b'_i \frac{\partial w}{\partial x'_i}$$

where $\mathfrak{b}' = T\mathfrak{b}$, i.e.

$$(2.8) \quad \begin{pmatrix} b'_1 \\ \vdots \\ b'_n \end{pmatrix} = \begin{pmatrix} l_{11} & \cdots & l_{1n} \\ \vdots & & \vdots \\ l_{n1} & \cdots & l_{nn} \end{pmatrix} \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix},$$

and lastly either $c'_0 = c_0$, or it might be written as $c_0 = \sum_{i=1}^n c'_i$, where c'_i are chosen arbitrarily, so far as their sum become c_0 .

Thus, on performing T , the partial differential equation (2.1) reduces to

$$(2.9) \quad \sum_{i=1}^n \left(a'_i \frac{\partial^2 w}{\partial x_i'^2} + b'_i \frac{\partial w}{\partial x_i'} + c'_i w \right) = f_1(x_1, x_2, \dots, x_n),$$

which form we have to treat below.

To find a complete integral, we write $f_1 = 0$:

$$(2.10) \quad \sum_{i=1}^n \left(a'_i \frac{\partial^2 w}{\partial x_i'^2} + b'_i \frac{\partial w}{\partial x_i'} + c'_i w \right) = 0.$$

Now, as usually made in Harmonic Analysis, we assume that

$$(2.11) \quad w = \prod_{i=1}^n u_i(x_i),$$

where every u_i is a function of x_i only. On substituting (2.11) in (2.10), and dividing out by w , we obtain

$$\sum_{i=1}^n \frac{1}{u_i} \left(a'_i \frac{d^2 u_i}{dx_i'^2} + b'_i \frac{du_i}{dx_i'} + c'_i u_i \right) = 0,$$

so that each summand ought to vanish reparamately:

$$(2.12) \quad a'_i \frac{d^2 u_i}{dx_i'^2} + b'_i \frac{du_i}{dx_i'} + c'_i u_i = 0, \quad (i = 1, 2, \dots, n),$$

with auxiliary equation

$$(2.13) \quad a'_i m^2 + b'_i m + c'_i = 0.$$

If the rank of matrix A be n , namely the determinant $|A| = |A'| = \prod_{i=1}^n a'_i \neq 0$, no a'_i could be zero, and consequently (2.13) should have two roots;

$$\alpha_i, \beta_i = \frac{1}{2a'_i} \{b'_i \pm \sqrt{b_i'^2 - 4a'_i c'_i}\} \quad (i = 1, 2, \dots, n)$$

and we obtain, as solutions

$$u_i(x_i) = A_i \exp \alpha_i x_i + B_i \exp \beta_i x_i \quad \text{if } \alpha_i \neq \beta_i,$$

$$\text{or else} \quad = (A_i x_i + B_i) \exp \alpha_i x_i \quad \text{if } \alpha_i = \beta_i.$$

Thus we get, as a complete integral of (2.9),

$$w = u_1(x_1) u_2(x_2) \dots u_n(x_n),$$

wich contains $3n - 1$ arbitrary constants A_i, B_i and c'_i with condition $\sum_{i=1}^n c'_i = c_0$.

If the rank of matrix A be $1 \leq r < n$, then equations (2.12) becomes

$$(2.14) \quad \begin{cases} \frac{1}{u_i} \left(a'_i \frac{d^2 u_i}{dx_i'^2} + b'_i \frac{du_i}{dx_i'} + c'_i u_i \right) = 0 & (i = 1, 2, \dots, r), \\ b'_i \frac{du_i}{dx_i'} + c'_i u_i = 0 & (i = r+1, \dots, n). \end{cases}$$

In the latter equations, every coefficients b'_i surely $\neq 0$, since, otherwise, the very variable x'_i does disappear, what contradicts our assumption of n independent variables, and those solutions are

$$u_i(x_i) = C_i \exp \left\{ \frac{c'_i}{b'_i} x_i \right\} \quad (i = r+1, \dots, n).$$

However, in a complete integral $w = \prod_{i=1}^n u_i(x_i)$, the constants C_i may be mingled in some A_j, B_j , so it contains only $n+2r-1$ arbitrary constants.

In the present case, it is somewhat difficult to discuss in general how to obtain a particular integral. We ought to find it ingeniously by problem. However, if it occurs that

$$f(x_1, \dots, x_n) \sim f(x_1^{(0)}, \dots, x_n^{(0)}) + \sum_{i=1}^n \left(\frac{\partial f}{\partial x_i^{(0)}} \right) (x_i - x_i^{(0)}) = d_0 + \sum_{i=1}^n d_i x_i,$$

as seen in the small oscillation about equilibrium position, then upon writing

$$d_0 \delta_i^1 + d_i x_i, \quad \text{with} \quad \delta_i^1 = 0 \quad (i=1) \quad \text{or} \quad = 0 \quad (i \neq 1)$$

in the right-handed side of (2.12) or (2.14), we may find the required particular integral.

§3. To illustrate how the above mentioned transformation to be executed actually, let us consider the case $n=3$:

$$(3.1) \quad \begin{aligned} A' \frac{\partial^2 w}{\partial x^2} + B' \frac{\partial^2 w}{\partial y^2} + C' \frac{\partial^2 w}{\partial z^2} + 2F \frac{\partial^2 w}{\partial y \partial z} + 2G \frac{\partial^2 w}{\partial z \partial x} + 2H \frac{\partial^2 w}{\partial x \partial y} \\ + 2K \frac{\partial w}{\partial x} + 2L \frac{\partial w}{\partial y} + 2M \frac{\partial w}{\partial z} + Nw = f(x, y, z), \end{aligned}$$

where A', B', \dots, N are given (real) constants, and $f(x, y, z)$ a given function. We conceive the problem of principal axes of the corresponding quadratic surface:

$$A'x^2 + B'y^2 + C'z^2 + 2Fyz + 2Gzx + 2Hxy = R.$$

To reduce this to the standard form we solve the characteristic equation

$$(3.2) \quad \Delta(\lambda) = \begin{vmatrix} A' - \lambda & H & G \\ H & B' - \lambda & F \\ G & F & C' - \lambda \end{vmatrix} = 0,$$

and let its 3 characteristic roots be $\lambda_1, \lambda_2, \lambda_3$.

i) When 3 roots are all different. Then, among the simultaneous equations

$$(3.3) \quad \begin{cases} (A' - \lambda_i) l_i + H m_i + G n_i = 0 \\ H l_i + (B' - \lambda_i) m_i + F n_i = 0 \\ G l_i + F m_i + (C' - \lambda_i) n_i = 0 \end{cases} \quad (i = 1, 2, 3),$$

there only two being independent, we have to take

$$\begin{aligned} (A' - \lambda_i) l_i + H m_i + G n_i &= 0 \\ (H + G) l_i + (B' + F - \lambda_i) m_i + (F + C' - \lambda_i) n_i &= 0. \end{aligned}$$

Whence the ratios $l_i : m_i : n_i$, and further on combining them with $l_i^2 + m_i^2 + n_i^2 = 1$, the respective values l_i, m_i, n_i ($i=1, 2, 3$) could be determined; moreover selecting the root-signs \pm for l_i, m_i, n_i adequately, it is always possible to make the Jacobian

$$J = \begin{vmatrix} l_1 & l_2 & l_3 \\ m_1 & m_2 & m_3 \\ n_1 & n_2 & n_3 \end{vmatrix} = 1.$$

ii) When 2 roots of (2.3) are equal, say $\lambda_2 = \lambda_3$. We can determine l_1, m_1, n_1 as in i). As to λ_2, λ_3 , we have

$$\begin{aligned} (A' - \lambda_2) l_2 + H m_2 + G n_2 &= 0, \\ (A' - \lambda_3) l_3 + H m_3 + G n_3 &= 0, \end{aligned}$$

and

$$l_2 l_3 + m_2 m_3 + n_2 n_3 = 0,$$

of which first two assure that the directions $(l_2, m_2, n_2), (l_3, m_3, n_3)$ are perpendicular to (l_1, m_1, n_1) . Here we ought to determine 4 ratio's $l_2 : m_2 : n_2, l_3 : m_3 : n_3$ from the above 3 equations, so that one unknown may be assumed at will. Hence, *e.g.* on taking $l_2=0$, we get $m_2 : n_2 = -G : H$, and consequently

$$(A' - \lambda_2) l_3 + H m_3 + G n_3 = 0, \quad -G m_3 + H n_3 = 0,$$

whence

$$l_3 : m_3 : n_3 = -(G^2 + H^2) : H(A' - \lambda_2) : G(A' - \lambda_3).$$

Thus in the above two cases we have already found a triple orthogonal system with Jacobien $J=1$. Hence making transformations

$$(3.4) \quad \begin{cases} \xi = l_1 x + m_1 y + n_1 z \\ \eta = l_2 x + m_2 y + n_2 z \\ \zeta = l_3 x + m_3 y + n_3 z \end{cases} \quad \text{or} \quad \begin{cases} x = l_1 \xi + l_2 \eta + l_3 \zeta \\ y = m_1 \xi + m_2 \eta + m_3 \zeta \\ z = n_1 \xi + n_2 \eta + n_3 \zeta \end{cases}$$

i.e.

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = T \begin{pmatrix} \xi \\ \eta \\ \zeta \end{pmatrix} \quad \text{with } T = \begin{pmatrix} l_1 & l_2 & l_3 \\ m_1 & m_2 & m_3 \\ n_1 & n_2 & n_3 \end{pmatrix}, \quad |T| = 1,$$

we have

$$A'x^2 + B'y^2 + C'z^2 + 2Fyz + 2Gzx + 2Hxy = \lambda_1\xi^2 + \lambda_2\eta^2 + \lambda_3\zeta^2.$$

Hence also by transformation

$$\begin{cases} \frac{\partial}{\partial x} = l_1 \frac{\partial}{\partial \xi} + l_2 \frac{\partial}{\partial \eta} + l_3 \frac{\partial}{\partial \zeta} \\ \frac{\partial}{\partial y} = m_1 \frac{\partial}{\partial \xi} + m_2 \frac{\partial}{\partial \eta} + m_3 \frac{\partial}{\partial \zeta} \\ \frac{\partial}{\partial z} = n_1 \frac{\partial}{\partial \xi} + n_2 \frac{\partial}{\partial \eta} + n_3 \frac{\partial}{\partial \zeta} \end{cases}, \quad J = \begin{vmatrix} l_1 & l_2 & l_3 \\ m_1 & m_2 & m_3 \\ n_1 & n_2 & n_3 \end{vmatrix} = 1,$$

the linear partial differential equation (3.1) becomes

$$\lambda_1 \frac{\partial^2 w}{\partial \xi^2} + \lambda_2 \frac{\partial^2 w}{\partial \eta^2} + \lambda_3 \frac{\partial^2 w}{\partial \zeta^2} + 2K_1 \frac{\partial w}{\partial \xi} + 2L_1 \frac{\partial w}{\partial \eta} + 2M_1 \frac{\partial w}{\partial \zeta} + N_1 w = f_1(\xi, \eta, \zeta).$$

Remark. When (3.2) has 3 equal roots $\lambda_1 = \lambda_2 = \lambda_3 = \lambda$, we have $\mathcal{A}(\lambda) = 0$, $\mathcal{A}'(\lambda) = 0$, $\mathcal{A}''(\lambda) = 2(A' + B' + C') - 6\lambda = 0$. Hence $\lambda = \frac{1}{3}(A' + B' + C')$ and this being substituted in $\mathcal{A}'(\lambda) = 0$, we get

$$(A' - B')^2 + (B' - C')^2 + (C' - A')^2 + 2F^2 + 2G^2 + 2H^2 = 0,$$

so that, for real coefficients, we must have $A' = B' = C'$, $F = G = H = 0$. Therefore the quadratic differential form in (3.1) becomes

$$A' \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) w,$$

i.e. Laplace's form and there is no need of transformation.

Example 3.

$$6 \frac{\partial^2 w}{\partial y^2} - 18 \frac{\partial^2 w}{\partial y \partial z} - 6 \frac{\partial^2 w}{\partial x \partial z} + 2 \frac{\partial^2 w}{\partial x \partial y} - 9 \frac{\partial w}{\partial x} + 5 \frac{\partial w}{\partial y} - 5 \frac{\partial w}{\partial z} + w = 0.$$

Here

$$|A| = \begin{vmatrix} 0 & 1 & -3 \\ 1 & 6 & -9 \\ -3 & -9 & 0 \end{vmatrix} = 0, \text{ and the matrix } A \text{ is of rank 2.}$$

Also from

$$\mathcal{A}(\lambda) = \begin{vmatrix} -\lambda & 1 & -3 \\ 1 & 6-\lambda & -9 \\ -3 & -9 & -\lambda \end{vmatrix} = -\lambda(\lambda+7)(\lambda-13) = 0,$$

we get 3 different roots 0, -7, 13, and correspondingly

$$\begin{aligned} l_1 : m_1 : n_1 &= -9 : 3 : 1 \\ l_2 : m_2 : n_2 &= 1 : 2 : 3 \\ l_3 : m_3 : n_3 &= 1 : 4 : -3 \end{aligned} \quad \text{so} \quad T = \begin{pmatrix} -9/\sqrt{91} & 3/\sqrt{91} & 1/\sqrt{91} \\ 1/\sqrt{14} & 2/\sqrt{14} & 3/\sqrt{14} \\ 1/\sqrt{26} & 4/\sqrt{26} & -3/\sqrt{26} \end{pmatrix}.$$

Therefore by transformation

$$\begin{pmatrix} \xi \\ \eta \\ \zeta \end{pmatrix} = T \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad \text{so also} \quad \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} = \bar{T} \begin{pmatrix} \frac{\partial}{\partial \xi} \\ \frac{\partial}{\partial \eta} \\ \frac{\partial}{\partial \zeta} \end{pmatrix}$$

the given partial differential equation is reduced to

$$7 \frac{\partial^2 w}{\partial \eta^2} - 13 \frac{\partial^2 w}{\partial \xi^2} + \sqrt{91} \frac{\partial w}{\partial \xi} - \sqrt{14} \frac{\partial w}{\partial \eta} + \sqrt{26} \frac{\partial w}{\partial \zeta} + w = 0.$$

This becomes, on assuming $w = X(\xi)Y(\eta)Z(\zeta)$

$$\left(\frac{\sqrt{91}}{X} \frac{dX}{d\xi} + 1 \right) + \frac{1}{Y} \left(\frac{d^2 Y}{d\eta^2} - \sqrt{14} \frac{dY}{d\eta} \right) - \frac{1}{Z} \left(13 \frac{d^2 Z}{d\zeta^2} - \sqrt{26} \frac{dZ}{d\zeta} \right) = 0.$$

Putting the expression under every bracket = 0, we get

$$X = A_1 \exp \left\{ -\frac{\xi}{\sqrt{91}} \right\}, \quad Y = A_2 \exp \left\{ \sqrt{\frac{2}{7}} \eta \right\} + B_2, \quad Z = A_3 \exp \left\{ \sqrt{\frac{2}{13}} \zeta \right\} + B_3,$$

so that a complete integral of the given partial differential equation is

$$w = \exp \left\{ \frac{1}{91} (-9x + 3y + z) \right\} \left[A_2 \exp \left\{ \frac{1}{7} (x + y + z) \right\} + B_2 \right] \times \\ \left[A_3 \exp \left\{ \frac{1}{13} (x + 4y - 3z) \right\} + B_3 \right],$$

where A_2, B_2, A_3, B_3 are arbitrary constants.

Example 4.

$$\frac{\partial^2 w}{\partial z^2} = 3 \frac{\partial w}{\partial x} + 4 \frac{\partial w}{\partial y}$$

Here

$$A = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

and its rank is 1. Assuming $w = X(x)Y(y)Z(z)$, the given equation becomes

$$\frac{1}{Z} \frac{d^2 Z}{dz^2} = \frac{3}{X} \frac{dX}{dx} + \frac{4}{Y} \frac{dY}{dy}.$$

Putting

$$\frac{3}{X} \frac{dX}{dx} = c_1, \quad \frac{4}{Y} \frac{dY}{dy} = c_2, \quad \frac{1}{Z} \frac{d^2 Z}{dz^2} = c_1 + c_2 = c,$$

we obtain

$$\begin{aligned} X &= k_1 \exp \left\{ \frac{c_1}{3} x \right\}, \quad Y = k_2 \exp \left\{ \frac{c_2}{4} y \right\}, \\ Z &= A_1 e^{\sqrt{c}z} + B_1 e^{-\sqrt{c}z}, & \text{if } c > 0, \\ &= A_1 \cos \sqrt{-c}z + B_1 \sin \sqrt{-c}z, & \text{if } c < 0, \\ &= A_1 + B_1 z, & \text{if } c = 0, \end{aligned}$$

where $c = c_1 + c_2$. Therefore, a complete integral of the given partial differential equation is

$$w = Z \exp \left\{ \frac{c_1}{3} x + \frac{c_2}{4} y \right\},$$

which contains 4 arbitrary constants A_1, B_1, c_1, c_2 .

The writer closes his paper by expressing his hearty thanks to Professor Y. Watanabe for his interest in this work and valuable suggestions.